

Torsionless Conformal Killing tensors and cofactor pair systems

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Lecture held at the Conference *State of-the-art in the classical separability theory for the differential equations*, Department of Mathematics, University of Linköping, January 6-11, 2004, organized by K. Marciniak and S. Rauch-Wojciechowski.

1. Introduction.

Let \mathbf{L} and \mathbf{G} be two contravariant symmetric 2-tensors on a manifold Q_n . Let us consider the characteristic equation

$$(1) \quad \det(\mathbf{L} - u \mathbf{G}) \equiv \det [L^{ij} - u G^{ij}] = 0.$$

We call the n roots of this algebraic equation the **eigenvalues of \mathbf{L} w.r. to \mathbf{G}** . In the following we shall examine the case in which:

- (a) \mathbf{G} is a metric tensor (of any signature) i.e., $\det \mathbf{G} \neq 0$.
- (b) \mathbf{L} has simple and real eigenvalues (u^i) w.r. to \mathbf{G} .
- (c) \mathbf{L} is a conformal Killing tensor w.r. to \mathbf{G} .
- (d) \mathbf{L} is torsionless w.r. to \mathbf{G} .

Let us call **L-system** a pair (\mathbf{L}, \mathbf{G}) of this kind, and **L-tensor** a tensor \mathbf{L} satisfying the above conditions. The interest of considering such a system is due to the following

Theorem 1. *The symmetric 2-tensors \mathbf{K}_a , $a = 0, 1, \dots, n-1$, defined by the sequence*

$$(2) \quad \mathbf{K}_0 = \mathbf{G}, \quad \mathbf{K}_a = \frac{1}{a} \operatorname{tr}(\mathbf{K}_{a-1} \mathbf{L}) \mathbf{G} - \mathbf{K}_{a-1} \mathbf{L}, \quad a \neq 0,$$

are independent Killing tensors in involution if and only if \mathbf{L} is a L-tensor.

Since all these tensors have common eigenvectors, they define a **Stäckel system** [KM, 1980] [B, 1993].

This means that: (i) the eigenvectors are **normal** i.e., orthogonally integrable or surface-forming: each one admits an orthogonal foliation of hypersurfaces (submanifolds of codimension 1). The set of these n foliations forms an **orthogonal web** which we call, in this case, **separable orthogonal web** or **Stäckel web**. (ii) Any local parametrization of this web i.e., any coordinate system (q^i) such that each foliation is locally described by equation $q^i = \text{constant}$, is a **separable orthogonal coordinate system**: these coordinates separate the geodesic HJE.

This theorem summarizes results established in [B, 1992, 1993] in the case of positive-definite metrics. However, under the assumption that the eigenvalues of \mathbf{L} are real, these results can be extended to indefinite metrics. This matter has been recently revisited in [B, 2004].

L-systems are only a special class of Stäckel (orthogonal separable) systems. However, they have the following nice property: *all the Killing tensors i.e., all the quadratic first integrals of the geodesic flow, which are related to the separation, can be constructed in a pure algebraic way by the sequence (2) starting from the tensor \mathbf{L} .* It is remarkable the fact that *this algebraic procedure does not require the knowledge of the eigenvalues of \mathbf{L} .* Hence, in this case, \mathbf{L} plays the role of a *generator* of the involutive algebra of first integrals associated with the separation. Furthermore, for finding the separable coordinates we have only to examine the tensor \mathbf{L} , which contains all information: the web orthogonal to its eigenvectors is indeed a Stäckel web.

Note that we do not require the functional independence of the eigenvalues u^i of \mathbf{L} ; some of them may be constant. The essential requirement is that they must be pointwise distinct, $u^i \neq u^j$. However,

Theorem 2. *If the eigenvalues (u^i) are independent functions, then they are separable coordinates.*

The functional independence of (u^i) is examined in [B, 2004]. It can be shown that,

Theorem 3. *The eigenvalues (u^i) of \mathbf{L} are independent if and only if \mathbf{L} is not invariant w.r. to a Killing vector of \mathbf{G} .*

In [B, 1992] it was shown that the definition (2) can be replaced by other equivalent definitions, which however, require the knowledge of the eigenvalues. Among them we recall the following one:

$$(3) \quad \mathbf{K}_a = \sum_{k=0}^a (-1)^k \sigma_{a-k} \mathbf{L}^k.$$

Here, $\sigma_p(\underline{u})$ denotes the elementary symmetric polynomial of order p in the variables $\underline{u} = (u^i)$.

In fact, sequences of the kind (2)-(3) appeared in the literature many years before within a completely different realm. In the *Ricci calculus* of Schouten [Sc, 1954] they are recalled from Souriau [So, 1950] and Fettis [F, 1950]: they are used for computing in a fast way the eigenvectors of a matrix \mathbf{L} (knowing the eigenvalues). In the book it is also remarked that, in our notation and terminology, the tensor

$$(4) \quad \mathbf{Q}(x) = \text{cof}(\mathbf{L} - x \mathbf{G})$$

is a polynomial of degree $n - 1$, whose coefficients are the tensors \mathbf{K}_a defined in (3).

However, if we go further in the past, we find in a paper of the young Levi-Civita [LC, 1896] the construction of geodesic first integrals by a formula similar to (4), in connection with the problem of finding the most general metric tensor admitting a geodesic correspondent. Indeed, if two (positive-definite) metric tensors $\tilde{\mathbf{G}}$ and \mathbf{G} are such that the eigenvalues of $\tilde{\mathbf{G}}$ w.r. to \mathbf{G} are simple, then they have the same unparametrized geodesics if and only if \mathbf{G} admits a L-tensor. This matter have been recently investigated by Bolsinov & Matveev [BM, 2003] and Crampin [C, 2003a, b]. Hence, *L-metric* may stand for *Levi-Civita-metric*: it is a metric admitting a L-tensor.

The aim of this lecture is to show how the scheme of L-systems fits with recent very interesting results of Rauch-Wojciechowski, Waksjö, Lundmark, Błaszak, Ibort, Magri, Marmo, Bolsinov, Matveev and Topalov. What illustrated here finds a more general setting based on the notion of **special conformal Killing tensor** introduced by Crampin, Sarlet and Thompson (see the references at the end of this paper). An extensive paper on this matter, entitled *Special tensors, equivalent dynamical systems and separation of variables*, is in preparation.

2. Notation and basic definitions.

If $\mathbf{L} = (L^{i\dots j})$ is a contravariant symmetric tensor on a manifold Q_n , then we denote by $P_{\mathbf{L}}$ the polynomial function on T^*Q defined by

$$P_{\mathbf{L}} = L^{i\dots j} p_i \cdots p_j.$$

Thus, we can define the symmetric tensor product \odot between these tensors by setting

$$P_{\mathbf{L} \odot \mathbf{K}} = P_{\mathbf{L}} P_{\mathbf{K}}.$$

By means of the Poisson bracket, defined by

$$\{F, G\} = \frac{\partial F}{\partial p_i} \frac{\partial G}{\partial q^i} - \frac{\partial G}{\partial p_i} \frac{\partial F}{\partial q^i},$$

we define a Lie-bracket by setting

$$P_{[\mathbf{L}, \mathbf{K}]} = \{P_{\mathbf{L}}, P_{\mathbf{K}}\}.$$

Two tensors are said to be **in involution** in $[\mathbf{L}, \mathbf{K}] = 0$. If \mathbf{G} is a metric tensor, then \mathbf{L} is a **conformal Killing tensor** (CKT) if

$$[\mathbf{L}, \mathbf{G}] = \mathbf{C} \odot \mathbf{G}.$$

If $\mathbf{C} = 0$ i.e., $[\mathbf{L}, \mathbf{G}] = 0$, then \mathbf{L} is a **Killing tensor**.

If $\mathbf{K}, \mathbf{L}, \dots$ are symmetric contravariant 2-tensors and if a metric tensor $\mathbf{G} = (G^{ij})$ is present, then we define their **algebraic product** \mathbf{LK} by setting

$$(\mathbf{KL})^{ij} = K^{ih} L^{kj} g_{hk},$$

where $[g_{ij}] = [G^{ij}]^{-1}$ are the covariant components of the metric. We say that \mathbf{K} and \mathbf{L} **commute** when $\mathbf{KL} - \mathbf{LK} = 0$. This gives the meaning of some formula of §1.

The **torsion** \mathbf{H} of a (1,1) tensor $\mathbf{T} = (T_i^j)$ is the (1,2)-tensor defined by

$$\boxed{\frac{1}{2} H_{ij}^k(\mathbf{T}) \doteq T_{[i}^h \partial_{|h|} L_{j]}^k - T_h^k \partial_{[i} T_{j]}^h]}$$

This definition does not depend on the choice of the coordinates and the partial derivatives $\partial_i = \partial/\partial q^i$ may be replaced by the covariant derivatives ∇_i w.r. to any symmetric

connection. When $\mathbf{H}(\mathbf{T}) = 0$, \mathbf{T} is said to be **torsionless**. The torsion has been introduced by Nijenhuis and Haantjes [N, 1951] [H, 1955] [FN, 1956], in order to establish criteria for the normality of the eigenvectors of a $(1, 1)$ tensor. If we start from a (symmetric) contravariant 2-tensor \mathbf{L} , then we can define the **torsion w.r. to a metric tensor** $[g_{ij}] = [G^{ij}]^{-1}$ by considering the associated $(1, 1)$ -tensor $L_i^j = L^{hj} g_{hi}$.

By the results of [N, 1951] [H, 1955] one can prove that,

Theorem 1. *If a symmetric tensor \mathbf{L} has simple and real eigenvalues w.r. to a metric \mathbf{G} , then $\mathbf{H}(\mathbf{L}) = 0$ if and only if*

- (i) *there are local coordinates (q^i) in which both \mathbf{L} and \mathbf{G} are diagonalized,*
- (ii) *$\partial_i u^j = 0$ for $i \neq j$, being u^i the eigenvalue corresponding to the eigenvector ∂_i .*

3. Elliptic-parabolic tensors on \mathbb{R}^n .

We shall work on the manifold $Q_n = \mathbb{R}^n$, referred to the Cartesian coordinates $\underline{x} = (x^\alpha)$ centered at the origin $O = (0, \dots, 0)$. We denote by $\mathbf{r} = OP$ the position vector of the generic point P : its Cartesian components coincides with the coordinates of P .

We shall study contravariant symmetric 2-tensors of the form

$$(1) \quad \mathbf{E} = \mathbf{C} + m \mathbf{r} \otimes \mathbf{r} + \mathbf{w} \odot \mathbf{r},$$

where $\mathbf{C} = (C^{\alpha\beta})$ is a constant symmetric contravariant 2-tensor, \mathbf{w} is a constant vector and $m \in \mathbb{R}$. Here, \odot denotes the symmetric tensor product (of vectors): $\mathbf{a} \odot \mathbf{b} \doteq \frac{1}{2}(\mathbf{a} \otimes \mathbf{b} + \mathbf{b} \otimes \mathbf{a})$. In the papers of S. Rauch and coworkers they are called **elliptic matrices** and denoted by \mathbf{G} ($\alpha = m, \beta = \frac{1}{2}\mathbf{w}$). Here we prefer to use the symbol \mathbf{G} for a generic metric although, as we shall see, we shall interpreted a tensor \mathbf{E} as a metric. Tensors of this kind were introduced in [B, 1992] as **planar inertia tensors** of a system of points with (positive or negative) masses, and related to the separable webs of \mathbb{R}^n endowed with the standard Euclidean metric. The scalar m is the total mass (it may be zero). It is remarkable the fact that a tensor \mathbf{E} is a torsionless CKT w.r. to the standard Euclidean metric, so that, if it has simple eigenvalues, it is a L-tensor and it generates a L-system. In [B, 1992] it is shown that the case $m \neq 0$ corresponds to the **elliptic-hyperbolic web** (i.e., to the separation in confocal elliptic-hyperbolic coordinates) as well as the case $m = 0$ and $\mathbf{w} \neq 0$ corresponds to the **parabolic web** (i.e., to the separation in parabolic coordinates). In these two cases we call \mathbf{E} **elliptic tensor** or **parabolic tensor**, respectively. The trivial case $m = 0$ and $\mathbf{w} = 0$ corresponds to the separation in Cartesian coordinates.

Our aim is to show that

Theorem 1. *If \mathbf{E} and $\tilde{\mathbf{E}}$ are two tensors of the kind (1) such that $\det(\tilde{\mathbf{E}}) \neq 0$ and \mathbf{E} has pointwise real simple eigenvalues w.r. to $\tilde{\mathbf{E}}$, then the tensor*

$$(2) \quad \mathbf{L} \doteq \det(\tilde{\mathbf{E}}) \mathbf{E}$$

is a torsionless conformal Killing tensor w.r. to the metric tensor

$$(3) \quad \mathbf{G} \doteq \det(\tilde{\mathbf{E}}) \tilde{\mathbf{E}}.$$

In other words, the pair (\mathbf{L}, \mathbf{G}) is a **L-system** on the manifold \mathbb{R}^n . For brevity we shall prove this theorem only in the case of an elliptic tensor $\tilde{\mathbf{E}}$ ($\tilde{m} \neq 0$).

Going back to the definition (1), we observe that \mathbf{E} has an affine character (it does not depend on a metric). Collecting results of [B, 1992] we can affirm that

Theorem 2. (i) If $m \neq 0$, then there exists a unique point O' such that \mathbf{E} assume the form

$$(4) \quad \mathbf{E} = \mathbf{C}' + m \mathbf{r}' \otimes \mathbf{r}', \quad \mathbf{r}' = O'P, \quad \mathbf{C}' = \mathbf{C} - \frac{1}{4m} \mathbf{w} \otimes \mathbf{w}.$$

(ii) If $m = 0$, then there exists a unique point O' such that $\mathbf{E}_{O'}(\mathbf{w}) = 0$ and \mathbf{w} is an eigenvector of \mathbf{E} at all points P of the straight line parallel to \mathbf{w} passing through O' .

In item (ii) we refer to the standard Euclidean metric of \mathbb{R}^n .

Proof. (i) If $O' \neq O$ is any other fixed point, then $\mathbf{r} = \mathbf{v} + \mathbf{r}'$, with $\mathbf{v} = OO'$. Since

$$\begin{cases} \mathbf{r} \otimes \mathbf{r} = \mathbf{r}' \otimes \mathbf{r}' + 2\mathbf{r}' \odot \mathbf{v} + \mathbf{v} \otimes \mathbf{v}, \\ \mathbf{w} \odot \mathbf{r} = \mathbf{w} \odot \mathbf{r}' + \mathbf{w} \odot \mathbf{v}, \end{cases}$$

it follows that

$$\mathbf{E} = \mathbf{C}' + m\mathbf{r}' \otimes \mathbf{r}' + \mathbf{w}' \odot \mathbf{r}', \quad \begin{cases} \mathbf{C}' = \mathbf{C} + \mathbf{v} \odot (m\mathbf{v} + \mathbf{w}), \\ \mathbf{w}' = \mathbf{w} + 2m\mathbf{v}. \end{cases}$$

For $m \neq 0$, by choosing

$$\mathbf{v} = -\frac{1}{2m} \mathbf{w},$$

we get $\mathbf{w}' = 0$ and (2). (ii) For $m = 0$ see [B, 1992]. ■

As a consequence of this theorem we can always find a point O , in general different from the point $\mathbf{0} \in \mathbb{R}^n$, such that a tensor \mathbf{E} has the form

$$(5) \quad \begin{cases} \mathbf{E} = \mathbf{C} + m \mathbf{r} \otimes \mathbf{r}, & \text{for } m \neq 0, \\ \mathbf{E} = \mathbf{C} + \mathbf{w} \odot \mathbf{r}, \quad \mathbf{C}(\mathbf{w}) = 0, & \text{for } m = 0. \end{cases}$$

Moreover, we can choose orthogonal Cartesian coordinates (x^α) with origin at O such that

$$(6) \quad \begin{cases} E^{\alpha\beta} = c^\alpha \delta^{\alpha\beta} + m x^\alpha x^\beta, & \text{for } m \neq 0, \\ E^{\alpha\beta} = c^\alpha \delta^{\alpha\beta} + \frac{w}{2} (x^\alpha \delta^{1\beta} + x^\beta \delta^{1\alpha}), \quad c^1 = 0, \quad w = w^1, & \text{for } m = 0. \end{cases}$$

4. Commutation relations.

A first remarkable property of the elliptic-parabolic tensors is the commutation formula

$$(1) \quad \boxed{[\mathbf{E}, \mathbf{E}'] = 2(\mathbf{A}' \odot \mathbf{E} - \mathbf{A} \odot \mathbf{E}')} \quad \begin{cases} \mathbf{A} \doteq 2m\mathbf{r} + \mathbf{w}, \\ \mathbf{A}' \doteq 2m'\mathbf{r} + \mathbf{w}'. \end{cases}$$

As we shall see below, the interest of this formula is that the Lie-commutator of \mathbf{E} and \mathbf{E}' is a sum of two terms which factorize in \mathbf{E} and \mathbf{E}' themselves. Note that the vectors \mathbf{A} , more precisely the vectors $\mathbf{N} = \frac{1}{2} \mathbf{A}$, have been already introduced in [RW, 2003].

To prove this formula we observe that, in Cartesian coordinates,

$$P_{\mathbf{E}} = C^{\alpha\beta} p_{\alpha} p_{\beta} + m (x^{\alpha} p_{\alpha})^2 + w^{\alpha} x^{\beta} p_{\alpha} p_{\beta},$$

where $C^{\alpha\beta}$ and w^{α} are constant. Then we can easily prove the following commutation relations:

$$\begin{cases} \{P_{\mathbf{C}}, P_{\mathbf{r}}\} = 2 P_{\mathbf{C}}, \\ \{P_{\mathbf{C}}, (P_{\mathbf{r}})^2\} = 4 P_{\mathbf{C}} P_{\mathbf{r}}, \\ \{P_{\mathbf{C}}, P_{\mathbf{w}} P_{\mathbf{r}}\} = 2 P_{\mathbf{C}} P_{\mathbf{w}}, \\ \{P_{\mathbf{w}}, P_{\mathbf{r}}\} = P_{\mathbf{w}}, \\ \{P_{\mathbf{r}} P_{\mathbf{w}}, (P_{\mathbf{r}})^2\} = 2 P_{\mathbf{w}} (P_{\mathbf{r}})^2. \end{cases}$$

Since $\{P_{\mathbf{C}}, P_{\mathbf{C}'}\} = 0$, $\{P_{\mathbf{C}}, P_{\mathbf{w}'}\} = 0$ and $\{P_{\mathbf{w}}, P_{\mathbf{w}'}\} = 0$, we have

$$\begin{aligned} \{P_{\mathbf{E}}, P_{\mathbf{E}'}\} &= \\ &= \{P_{\mathbf{C}} + m P_{\mathbf{r}}^2 + P_{\mathbf{w}} P_{\mathbf{r}}, P_{\mathbf{C}'} + m' P_{\mathbf{r}}^2 + P_{\mathbf{w}'} P_{\mathbf{r}}\} \\ &= \{P_{\mathbf{C}}, m' P_{\mathbf{r}}^2 + P_{\mathbf{w}'} P_{\mathbf{r}}\} + \{m P_{\mathbf{r}}^2, P_{\mathbf{C}'} + P_{\mathbf{w}'} P_{\mathbf{r}}\} \\ &\quad + \{P_{\mathbf{w}} P_{\mathbf{r}}, P_{\mathbf{C}'} + m' P_{\mathbf{r}}^2 + P_{\mathbf{w}'} P_{\mathbf{r}}\} - \dots \text{(similar terms with ' interchanged)} \\ &= 2m' P_{\mathbf{r}} \{P_{\mathbf{C}}, P_{\mathbf{r}}\} + P_{\mathbf{w}'} \{P_{\mathbf{C}}, P_{\mathbf{r}}\} + 2m P_{\mathbf{r}} \{P_{\mathbf{r}}, P_{\mathbf{C}'}\} + m P_{\mathbf{r}} \{P_{\mathbf{r}}^2, P_{\mathbf{w}'}\} + P_{\mathbf{w}} \{P_{\mathbf{r}}, P_{\mathbf{C}'}\} \\ &\quad + m' P_{\mathbf{r}} \{P_{\mathbf{w}}, P_{\mathbf{r}}^2\} + \{P_{\mathbf{w}} P_{\mathbf{r}}, P_{\mathbf{w}'}\} P_{\mathbf{r}} + \{P_{\mathbf{w}} P_{\mathbf{r}}, P_{\mathbf{r}}\} P_{\mathbf{w}'} - \dots \\ &= 2(2m' P_{\mathbf{r}} + P_{\mathbf{w}'} P_{\mathbf{r}}) P_{\mathbf{C}} - 4m P_{\mathbf{r}} P_{\mathbf{C}'} - 2m P_{\mathbf{r}}^2 P_{\mathbf{w}'} - 2P_{\mathbf{w}} P_{\mathbf{C}'} + 2m' P_{\mathbf{r}}^2 P_{\mathbf{w}} - \dots \\ &= 2(2m' P_{\mathbf{r}} + P_{\mathbf{w}'} P_{\mathbf{r}}) P_{\mathbf{C}} - 2(2m P_{\mathbf{r}} + P_{\mathbf{w}}) P_{\mathbf{C}'} + 2P_{\mathbf{r}}^2 (m' P_{\mathbf{w}} - m P_{\mathbf{w}'} P_{\mathbf{r}}) - \dots \end{aligned}$$

$$\boxed{\{P_{\mathbf{E}}, P_{\mathbf{E}'}\} = 2 \left[(2m' P_{\mathbf{r}} + P_{\mathbf{w}'} P_{\mathbf{r}}) P_{\mathbf{C}} - (2m P_{\mathbf{r}} + P_{\mathbf{w}}) P_{\mathbf{C}'} + P_{\mathbf{r}}^2 (m' P_{\mathbf{w}} - m P_{\mathbf{w}'} P_{\mathbf{r}}) \right]}$$

It is a surprising fact that, by introducing the vectors \mathbf{A} we get

$$\begin{aligned} P_{\mathbf{A}'} P_{\mathbf{E}} - P_{\mathbf{A}} P_{\mathbf{E}'} &= (2m' P_{\mathbf{r}} + P_{\mathbf{w}'} P_{\mathbf{r}}) (P_{\mathbf{C}} + m (P_{\mathbf{r}})^2 + P_{\mathbf{r}} P_{\mathbf{w}}) - \dots \\ &= (2m' P_{\mathbf{r}} + P_{\mathbf{w}'} P_{\mathbf{r}}) P_{\mathbf{C}} + m P_{\mathbf{r}}^2 P_{\mathbf{w}'} + 2m' P_{\mathbf{r}}^2 P_{\mathbf{w}} - \\ &\quad - (2m P_{\mathbf{r}} + P_{\mathbf{w}}) P_{\mathbf{C}'} - m' P_{\mathbf{r}}^2 P_{\mathbf{w}} - 2m P_{\mathbf{r}}^2 P_{\mathbf{w}'} P_{\mathbf{r}}, \end{aligned}$$

so that

$$\boxed{\{P_{\mathbf{E}}, P_{\mathbf{E}'}\} = 2 (P_{\mathbf{A}'} P_{\mathbf{E}} - P_{\mathbf{A}} P_{\mathbf{E}'})}$$

which is equivalent to (1).

5. Elliptic metric tensors.

Let us consider an elliptic tensor \mathbf{E} , $m \neq 0$. As we have seen, §1, (2), we can always find orthogonal Cartesian coordinates (x^{α}) such that

$$(1) \quad \boxed{E^{\alpha\beta} = \delta^{\alpha\beta} c^{\alpha} + m x^{\alpha} x^{\beta}}$$

Note that the constants c^α are the eigenvalues of \mathbf{C} i.e., of \mathbf{E} at $\mathbf{r} = 0$, w.r. to the standard Euclidean metric. Let us consider a contravariant symmetric tensor of the kind

$$e_{\alpha\beta} = \delta_{\alpha\beta} \varepsilon^\alpha - \xi \varepsilon^\alpha \varepsilon^\beta x^\alpha x^\beta.$$

We have

$$\begin{aligned} E^{\gamma\beta} e_{\alpha\beta} &= (\delta^{\gamma\beta} c^\gamma + m x^\gamma x^\beta) (\delta_{\alpha\beta} \varepsilon^\alpha - \xi \varepsilon^\alpha \varepsilon^\beta x^\alpha x^\beta) \\ &= \delta_\alpha^\gamma c^\gamma \varepsilon^\alpha + m x^\gamma x^\alpha \varepsilon^\alpha - \xi (\varepsilon^\gamma c^\gamma x^\gamma \varepsilon^\alpha x^\alpha + m x^\gamma \varepsilon^\alpha x^\alpha \sum_\beta \varepsilon^\beta (x^\beta)^2) \\ &= \delta_\alpha^\gamma c^\gamma \varepsilon^\alpha + x^\gamma x^\alpha \varepsilon^\alpha [m - \xi (\varepsilon^\gamma c^\gamma + m \sum_\beta \varepsilon^\beta (x^\beta)^2)]. \end{aligned}$$

Equation $E^{\gamma\beta} e_{\alpha\beta} = \delta_\alpha^\gamma$ is satisfied if and only if

$$c^\alpha \varepsilon^\alpha = 1, \quad \xi (\varepsilon^\gamma c^\gamma + m \sum_\beta \varepsilon^\beta (x^\beta)^2) = m.$$

This shows that

Theorem 1. *The tensor \mathbf{E} (with $m \neq 0$) is a metric tensor if and only if all $c^\alpha \neq 0$. The covariant metric $e_{\alpha\beta}$ is*

$$(2) \quad \boxed{e_{\alpha\beta} = \varepsilon^\alpha \delta_{\alpha\beta} - \xi \varepsilon^\alpha \varepsilon^\beta x^\alpha x^\beta, \quad \xi = \left(\frac{1}{m} + \sum_\beta \varepsilon^\beta (x^\beta)^2 \right)^{-1}, \quad \varepsilon^\alpha = \frac{1}{c_\alpha}}$$

The metric is not defined on the hyperquadric

$$(3) \quad 1 + m \sum_\beta \varepsilon^\beta (x^\beta)^2 = 0.$$

Besides ξ it is convenient to consider the quantity

$$\Sigma \doteq \sum_\alpha \varepsilon^\alpha (x^\alpha)^2,$$

so that

$$(4) \quad \xi = \frac{m}{1 + m\Sigma}, \quad \Sigma = \frac{1}{\xi} - \frac{1}{m}, \quad 1 - \xi \Sigma = \frac{\xi}{m}.$$

The tensor $e_{\alpha\beta}$ has a remarkable geometrical interpretation, which will be of help in the following. In $\mathbb{R}^{n+1} = \mathbb{R}^n \times \mathbb{R} = (x^\alpha, x^{n+1})$, with the canonical basis $(\mathbf{c}_\alpha, \mathbf{t})$, we consider the surface \mathbb{H}_n described by the vector-parametric equation

$$(6) \quad \mathbf{q} = x^\alpha \mathbf{c}_\alpha + \sqrt{\frac{1}{m} + \sum_\alpha \varepsilon^\alpha (x^\alpha)^2} \mathbf{t} = \mathbf{r} + z \mathbf{t}, \quad z \doteq \xi^{-\frac{1}{2}},$$

with domain $D_+ \subset \mathbb{R}^n$ where $\boxed{\xi > 0}$. Since $\partial_\alpha z = z^{-1} \varepsilon^\alpha x^\alpha$, the natural basis of the tangent spaces of \mathbb{H}_n is

$$\mathbf{e}_\alpha \doteq \partial_\alpha \mathbf{q} = \mathbf{c}_\alpha + z^{-1} \varepsilon^\alpha x^\alpha \mathbf{t} = \mathbf{c}_\alpha \xi^{\frac{1}{2}} \varepsilon^\alpha x^\alpha \mathbf{t}.$$

If in \mathbb{R}^{n+1} we introduce the metric tensor

$$(7) \quad \mathbf{g}(\mathbf{u}, \mathbf{v}) = \sum_{\alpha} \varepsilon^{\alpha} u^{\alpha} v^{\alpha} - u^{n+1} v^{n+1},$$

then

$$(8) \quad \begin{cases} \mathbf{g}(\mathbf{c}_{\alpha}, \mathbf{c}_{\beta}) = \delta_{\alpha\beta} \varepsilon^{\alpha}, \\ \mathbf{g}(\mathbf{c}_{\alpha}, \mathbf{t}) = 0, \end{cases} \quad \begin{cases} \mathbf{g}(\mathbf{t}, \mathbf{t}) = -1, \\ \mathbf{g}(\mathbf{q}, \mathbf{q}) = -1/m. \end{cases}$$

It follows that the metric tensor \mathbf{g} induces on \mathbb{H}_n the metric tensor

$$e_{\alpha\beta} \doteq \mathbf{g}(\mathbf{e}_{\alpha}, \mathbf{e}_{\beta}) = \delta_{\alpha\beta} \varepsilon^{\alpha} - \frac{1}{z^2} \varepsilon^{\alpha} \varepsilon^{\beta} x^{\alpha} x^{\beta}.$$

This metric tensor, reduced to \mathbb{R}^n , is exactly that defined in (2). The conclusion is that *we can work on the covariant metric tensor \mathbf{E} by interpreting it as the metric tensor induced on \mathbb{H}_n by the pseudo-Euclidean metric (7)*

Theorem 2. *Let (p, q) be the number of the positive and negative constants c^{α} , respectively. Then, for $m > 0$ the signature of \mathbf{E} is (p, q) and for $m < 0$ the signature is $(p - 1, q + 1)$.*

Proof. The vector \mathbf{q} is orthogonal to \mathbb{H}_n ,

$$\mathbf{g}(\mathbf{q}, \mathbf{e}_{\alpha}) = 0.$$

The signature of \mathbf{g} is $(p, q + 1)$. From (8) we see that if $m > 0$, \mathbf{q} is timelike. Since it is orthogonal to \mathbb{H}_n , it follows that the signature of the metric induced on \mathbb{H}_n hence, the signature of \mathbf{E} is (p, q) . If $m < 0$, \mathbf{q} is spacelike, so that the signature is $(p - 1, q + 1)$. ■

Theorem 3. *The metric \mathbf{E} has constant negative curvature.*

$$\textit{Proof.} \quad \partial_{\beta} \mathbf{e}_{\alpha} = \varepsilon^{\alpha} \partial_{\beta} \frac{x^{\alpha}}{z} \mathbf{t} = \varepsilon^{\alpha} \left(\frac{1}{z} \delta_{\alpha\beta} - \frac{x^{\alpha}}{z^2} \partial_{\beta} z \right) \mathbf{t} = \frac{\varepsilon^{\alpha}}{z} \left(\delta_{\alpha\beta} - \frac{\varepsilon^{\beta} x^{\alpha} x^{\beta}}{z^2} \right) \mathbf{t}.$$

$$(9) \quad \partial_{\beta} \mathbf{e}_{\alpha} = \frac{1}{z} e_{\alpha\beta} \mathbf{t}.$$

We consider the unit vector orthogonal to \mathbb{H}_n , $\mathbf{u} = |m|^{\frac{1}{2}} \mathbf{q}$, for computing the second fundamental form of \mathbb{H}_n ,

$$B_{\alpha\beta} = \mathbf{g}(\partial_{\alpha} \mathbf{e}_{\beta}, \mathbf{u}) = -|m|^{\frac{1}{2}} e_{\alpha\beta}.$$

The eigenvalues of $B_{\alpha\beta}$ w.r. to the metric $e_{\alpha\beta}$ are all equal to $-|m|^{\frac{1}{2}}$. This shows that \mathbb{H}_n has a constant intrinsic curvature. The sign of this curvature is a matter of convention. We note that the eigenvalues do not depend on the sign of the ε^{α} . In the case where they are all positive, the metric \mathbf{g} is a Minkowski metric, and \mathbb{H}_n is the hyperboloid of the unit timelike vectors oriented in the future. Its constant curvature is known to be, by convention, negative (as well as for a unit sphere the curvature is assumed to be positive). ■

Theorem 4. *The Christoffel symbols of the metric $e_{\alpha\beta}$ are*

$$\boxed{\Gamma_{\alpha\beta}^{\gamma} = -m x^{\gamma} e_{\alpha\beta}}$$

Proof. By definition, $\Gamma_{\alpha\beta,\mu} = \mathbf{E}(\partial_\alpha \mathbf{e}_\beta, \mathbf{e}_\mu) = \mathbf{g}(\partial_\alpha \mathbf{e}_\beta, \mathbf{e}_\mu)$. Because of (9) and (6),

$$\Gamma_{\alpha\beta,\mu} = \frac{1}{z} e_{\alpha\beta} \mathbf{g}(\mathbf{e}_\mu, \mathbf{t}) = \frac{1}{z} e_{\alpha\beta} \cdot (-\xi^{\frac{1}{2}} \varepsilon^\mu x^\mu) = -\xi \varepsilon^\mu x^\mu e_{\alpha\beta}.$$

$$\begin{aligned} \Gamma_{\alpha\beta}^\gamma &= E^{\gamma\mu} \Gamma_{\alpha\beta,\mu} = -(c^\gamma \delta^{\gamma\mu} + m x^\gamma x^\mu) (\xi \varepsilon^\mu x^\mu e_{\alpha\beta}) \\ &= -\xi e_{\alpha\beta} (c^\gamma \varepsilon^\gamma x^\gamma + m x^\gamma \sum_\mu \varepsilon^\mu (x^\mu)^2) = -m \xi e_{\alpha\beta} x^\gamma \left(\frac{1}{m} + \sum_\mu \varepsilon^\mu (x^\mu)^2 \right). \quad \blacksquare \end{aligned}$$

For any contravariant 2-tensor $T^{\alpha\beta}$,

$$(10) \quad \nabla_\alpha T^{\beta\gamma} = \partial_\alpha T^{\beta\gamma} + \Gamma_{\alpha\rho}^\beta T^{\rho\gamma} + \Gamma_{\alpha\rho}^\gamma T^{\beta\rho} = \partial_\alpha T^{\beta\gamma} - m(x^\beta T_\alpha^\gamma + x^\gamma T_\alpha^\beta).$$

For any $(1,1)$ tensor T_α^β ,

$$\nabla_\alpha T_\beta^\gamma = \partial_\alpha T_\beta^\gamma + \Gamma_{\alpha\rho}^\gamma T_\beta^\rho - \Gamma_{\alpha\beta}^\sigma T_\sigma^\gamma = \partial_\alpha T_\beta^\gamma - m(x^\gamma T_{\alpha\beta} - x^\sigma T_\sigma^\gamma e_{\alpha\beta}), \quad e_{\alpha\rho} T_\beta^\rho = T_{\alpha\beta}.$$

We consider the case

$$T^{\alpha\beta} = \tilde{E}^{\alpha\beta} = \tilde{C}^{\alpha\beta} + \tilde{m} x^\alpha x^\beta + \frac{1}{2} (\tilde{w}^\alpha x^\beta + \tilde{w}^\beta x^\alpha),$$

where $\tilde{C}^{\alpha\beta}$ and \tilde{w}^α are constant. From (10),

$$\nabla_\alpha T^{\beta\gamma} = \tilde{m} (\delta_\alpha^\beta x^\gamma + \delta_\alpha^\gamma x^\beta) + \frac{1}{2} (\tilde{w}^\beta \delta_\alpha^\gamma + \tilde{w}^\gamma \delta_\alpha^\beta) - m(x^\beta T_\alpha^\gamma + x^\gamma T_\alpha^\beta).$$

We observe that

$$e_{\alpha\beta} x^\alpha = \delta_{\alpha\beta} \varepsilon^\alpha x^\alpha - \xi \varepsilon^\alpha \varepsilon^\beta x^\beta (x^\alpha)^2 = \varepsilon^\beta x^\beta (1 - \xi \Sigma) = \frac{\xi}{m} \varepsilon^\beta x^\beta.$$

Thus,

$$\begin{aligned} \nabla_\alpha T_\sigma^\beta &= \nabla_\alpha T^{\beta\gamma} e_{\gamma\sigma} \\ &= e_{\gamma\sigma} (\tilde{m} (\delta_\alpha^\beta x^\gamma + \delta_\alpha^\gamma x^\beta) + \frac{1}{2} (\tilde{w}^\beta \delta_\alpha^\gamma + \tilde{w}^\gamma \delta_\alpha^\beta) - m(x^\beta T_\alpha^\gamma + x^\gamma T_\alpha^\beta)) \\ &= \tilde{m} (\delta_\alpha^\beta \frac{\xi}{m} \varepsilon^\sigma x^\sigma + e_{\alpha\sigma} x^\beta) + \frac{1}{2} (\tilde{w}^\beta e_{\alpha\sigma} + \tilde{w}_\sigma \delta_\alpha^\beta) - m x^\beta T_{\alpha\sigma} - \xi \varepsilon^\sigma x^\sigma T_\alpha^\beta. \end{aligned}$$

This proves the useful formula

$$(11) \quad \boxed{\nabla_\alpha \tilde{E}_\sigma^\beta = x^\beta (\tilde{m} e_{\alpha\sigma} - m \tilde{E}_{\alpha\sigma}) + \frac{\xi}{m} \varepsilon^\sigma x^\sigma (\tilde{m} \delta_\alpha^\beta - m \tilde{E}_\alpha^\beta) + \frac{1}{2} (\tilde{w}^\beta e_{\alpha\sigma} + \tilde{w}_\sigma \delta_\alpha^\beta)}$$

6. The torsion of \mathbf{E} w.r. to $\tilde{\mathbf{E}}$.

Let \mathbf{E} be an elliptic-parabolic tensor. Assume that $\tilde{\mathbf{E}}$ is an elliptic metric tensor ($\tilde{m} \neq 0$). We apply to it all the results of the preceding section. We recall the last formula (by interchanging \mathbf{E} with $\tilde{\mathbf{E}}$):

$$(1) \quad \tilde{\nabla}_\sigma E_\beta^\gamma = x^\gamma (m \tilde{e}_{\sigma\beta} - \tilde{m} E_{\sigma\beta}) + \frac{\tilde{\xi}}{\tilde{m}} \tilde{\varepsilon}^\beta x^\beta (m \delta_\sigma^\gamma - \tilde{m} E_\sigma^\gamma) + \frac{1}{2} (w^\gamma \tilde{e}_{\sigma\beta} + w_\beta \delta_\sigma^\gamma).$$

Hence,

$$\begin{aligned}
E_\alpha^\sigma \tilde{\nabla}_\sigma E_\beta^\gamma &= \\
&= E_\alpha^\sigma \left[x^\gamma (m \tilde{e}_{\sigma\beta} - \tilde{m} E_{\sigma\beta}) + \frac{\tilde{\xi}}{\tilde{m}} \tilde{\varepsilon}^\beta x^\beta (m \delta_\sigma^\gamma - \tilde{m} E_\sigma^\gamma) + \frac{1}{2} (w^\gamma \tilde{e}_{\sigma\beta} + w_\beta \delta_\sigma^\gamma) \right] \\
&= x^\gamma (m E_{\alpha\beta} - \tilde{m} E_{\alpha\beta}^2) + \frac{\tilde{\xi}}{\tilde{m}} \tilde{\varepsilon}^\beta x^\beta (m E_\alpha^\gamma - \tilde{m} (E^2)_\alpha^\gamma) + \frac{1}{2} (w^\gamma E_{\alpha\beta} + w_\beta E_\alpha^\gamma).
\end{aligned}$$

This proves that

$$(2) \quad E_\alpha^\sigma \tilde{\nabla}_\sigma E_\beta^\gamma = \frac{\tilde{\xi}}{\tilde{m}} \tilde{\varepsilon}^\beta x^\beta (m E_\alpha^\gamma - \tilde{m} (E^2)_\alpha^\gamma) + \frac{1}{2} w_\beta E_\alpha^\gamma + \dots$$

\dots = terms symmetric in (α, β) . On the other hand, we can write (1) in the form

$$\tilde{\nabla}_\alpha E_\beta^\rho = \frac{\tilde{\xi}}{\tilde{m}} \tilde{\varepsilon}^\beta x^\beta (m \delta_\alpha^\rho - \tilde{m} E_\alpha^\rho) + \frac{1}{2} w_\beta \delta_\alpha^\rho + \dots,$$

so that

$$E_\rho^\gamma \tilde{\nabla}_\alpha E_\beta^\rho = \frac{\tilde{\xi}}{\tilde{m}} \varepsilon^\beta x^\beta (m E_\alpha^\gamma - \tilde{m} (E^2)_\alpha^\gamma) + \frac{1}{2} w_\beta E_\alpha^\gamma + \dots$$

The comparison with (2) shows that

$$\boxed{\mathbf{H}(\mathbf{E}) = 0}$$

Theorem 1. *The elliptic-parabolic tensor \mathbf{E} is torsionless w.r. to the elliptic metric $\tilde{\mathbf{E}}$.*

7. Elliptic-parabolic tensors as conformal Killing tensors.

It can be shown [B,1992] that for $E^{\alpha\beta} = c^\alpha \delta^{\alpha\beta} + m x^\alpha x^\beta$,

$$(1) \quad E \doteq \det[E^{\alpha\beta}] = \sigma_n(\underline{c}) + m \sum_\alpha \sigma_{n-1}^\alpha(\underline{c})(x^\alpha)^2.$$

It follows that

$$(2) \quad \partial_\alpha E = 2 m \sigma_{n-1}^\alpha x^\alpha, \quad E^{\alpha\beta} \partial_\alpha E = 2 m \sigma_{n-1}^\alpha x^\alpha (c^\alpha \delta^{\alpha\beta} + m x^\alpha x^\beta) = 2 m E x^\beta.$$

Let us recall the commutation relation

$$[\mathbf{E}, \tilde{\mathbf{E}}] = 2 (\tilde{\mathbf{A}} \odot \mathbf{E} - \mathbf{A} \odot \tilde{\mathbf{E}}), \quad \mathbf{A} = 2m\mathbf{r} + \mathbf{w}, \quad \tilde{\mathbf{A}} = 2\tilde{m}\mathbf{r} + \tilde{\mathbf{w}}.$$

For any function f on \mathbb{R}^n we have

$$\begin{aligned}
[f\mathbf{E}, f\tilde{\mathbf{E}}] &= f^2 [\mathbf{E}, \tilde{\mathbf{E}}] + f [\mathbf{E}, f] \odot \tilde{\mathbf{E}} + f [f, \tilde{\mathbf{E}}] \odot \mathbf{E} \\
&= 2 f^2 (\tilde{\mathbf{A}} \odot \mathbf{E} - \mathbf{A} \odot \tilde{\mathbf{E}}) + f [\mathbf{E}, f] \odot \tilde{\mathbf{E}} + f [f, \tilde{\mathbf{E}}] \odot \mathbf{E}.
\end{aligned}$$

Thus, an equation of the kind $[f\mathbf{E}, f\tilde{\mathbf{E}}] = \mathbf{V} \odot \tilde{\mathbf{E}}$ is fulfilled iff

$$2f\tilde{\mathbf{A}} + [f, \tilde{\mathbf{E}}] = 0, \quad \text{i.e.,} \quad [\tilde{\mathbf{E}}, f] = 2(2\tilde{m}\mathbf{r} + \tilde{\mathbf{w}})f.$$

For $\tilde{m} \neq 0$ we can consider $\tilde{\mathbf{w}} = 0$ without loss of generality: $[\tilde{\mathbf{E}}, f] = 4\tilde{m}f\mathbf{r}$.

This equation is equivalent to

$$\tilde{E}^{\alpha\beta}\partial_{\alpha}f = 2\tilde{m}f x^{\beta}.$$

Due to (2), this equation is solved by $f = \det(\tilde{\mathbf{E}}) = \det(\tilde{E}^{\alpha\beta})$. Thus,

Theorem 1. *If the tensor $\mathbf{G} = \det(\tilde{\mathbf{E}})\tilde{\mathbf{E}}$ is a metric tensor, then $\mathbf{L} = \det(\tilde{\mathbf{E}})\mathbf{E}$ is a conformal Killing tensor.*

Theorem 2. *The tensor \mathbf{L} is torsionless w.r. to the metric \mathbf{G} .*

Proof. \mathbf{E} is torsionless w.r. to $\tilde{\mathbf{E}}$. The eigenvalues and the eigenvectors of \mathbf{E} w.r. to $\tilde{\mathbf{E}}$ are the same of \mathbf{L} w.r. to \mathbf{G} . If the eigenvalues of \mathbf{E} are simple and real, then also \mathbf{L} is torsionless. ■

This proves Theorem 1 of §3.

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